Construction of QMC Finite Element Methods for Elliptic PDEs with Random Coefficients

SFB Kooperations-Workshop (virtual)

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Joint work with Lukas Herrmann and Peter Kritzer January 22, 2021





Problem statement

Problem setting

Consider the parametric elliptic Dirichlet problem given by

$$\begin{aligned} -\nabla \cdot (\boldsymbol{a}(\boldsymbol{x},\boldsymbol{y}) \nabla \boldsymbol{u}(\boldsymbol{x},\boldsymbol{y})) &= f(\boldsymbol{x}) \quad \text{for } \boldsymbol{x} \in D \subset \mathbb{R}^d, \\ \boldsymbol{u}(\boldsymbol{x},\boldsymbol{y}) &= 0 \qquad \text{for } \boldsymbol{x} \text{ on } \partial D, \end{aligned}$$

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Assumptions:

- gradients are taken w.r.t. \boldsymbol{x} and we assume $f: D \to \mathbb{R}$ lies in $L^2(D)$
- the stochastic variable $\mathbf{y} = (y_j)_{j\geq 1}$ is uniformly distributed on $U = \left[-\frac{1}{2}, \frac{1}{2}\right]^{\mathbb{N}}$ with uniform product measure $\mu(\mathrm{d}\mathbf{y}) = \bigotimes_{j\geq 1} \mathrm{d}y_j$
- the parametric diffusion coefficient $a(\mathbf{x}, \mathbf{y})$ depends on the y_j via:

$$a(oldsymbol{x},oldsymbol{y}) = a_0(oldsymbol{x}) + \sum_{j\geq 1} y_j \, \psi_j(oldsymbol{x})$$

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Alternatively:
$$a(\mathbf{x}, \mathbf{y}) = \exp(Z(\mathbf{x}, \mathbf{y}))$$
 with
 $Z(\mathbf{x}, \mathbf{y}) = \sum_{j \ge 1} y_j \psi_j(\mathbf{x})$ and $y_j \sim \mathcal{N}(0, 1)$
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Illustration of the random field a(x, y)

Different realizations¹ of the random field a(x, y)



(a) rough random field sample



(b) rough random field sample





(c) smooth random field sample (Matérn kernel) (d) smooth random field sample (Matérn kernel)

¹By courtesy of Pieterjan Robbe

Solutions of the PDE

Consider the Sobolev space $V = H_0^1(D)$ of functions which vanish on the boundary ∂D with norm

$$\|\boldsymbol{v}\|_{\boldsymbol{V}} := \left(\int_{D}\sum_{j=1}^{d}|\partial_{\boldsymbol{x}_{j}}\boldsymbol{v}(\boldsymbol{x})|^{2}\,\mathrm{d}\boldsymbol{x}\right)^{\frac{1}{2}} = \|\nabla\boldsymbol{v}\|_{L^{2}(D)}.$$

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Variational formulation of PDE

For given $f \in V^*$ and $\mathbf{y} \in U$, find $u(\cdot, \mathbf{y}) \in V$ such that

$$egin{aligned} \mathcal{A}(oldsymbol{y}; u(\cdot, oldsymbol{y}), v) &= \langle f, v
angle_{V^* imes V} = \int_D f(oldsymbol{x}) v(oldsymbol{x}) \, \mathrm{d}oldsymbol{x} & ext{ for all } v \in V, \end{aligned}$$

with parametric bilinear form $A: \mathit{U} \times \mathit{V} \times \mathit{V} \to \mathbb{R}$ given by

$$A(\mathbf{y}; w, v) := \int_D a(\mathbf{x}, \mathbf{y}) \, \nabla w(\mathbf{x}) \cdot \nabla v(\mathbf{x}) \, \mathrm{d}\mathbf{x} \quad \text{for} \quad w, v \in V.$$

Goal: For a bounded linear functional $G \in V^*$, we want to approximate

$$\mathbb{E}[G(u)] := \lim_{s \to \infty} \int_{\left[-\frac{1}{2}, \frac{1}{2}\right]^s} G(u(\cdot, (y_1, \dots, y_s, 0, 0, \dots))) \, \mathrm{d}y_1 \cdots \, \mathrm{d}y_s$$

by randomized rank-1 lattice rules (or other QMC rules) of the form

$$Q_N(G(u_h^s), \mathbf{Z}, \mathbf{\Delta}) = \frac{1}{N} \sum_{k=0}^{N-1} G\left(u_h^s\left(\cdot, \left\{\frac{k\mathbf{Z}}{N} + \mathbf{\Delta}\right\} - \left(\frac{1}{2}, \dots, \frac{1}{2}\right)\right)\right)$$

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• This problem has been extensively studied, see, e.g., Kuo, Schwab, Sloan (2012) or for a broader review article, see Kuo, Nuyens (2016).

The mean square error can be bounded by

$$\mathbb{E}_{\Delta}\left[\left|\mathbb{E}[G(u)] - Q_{N}(G(u_{h}^{s}), z, \Delta)\right|^{2}\right] \leq \mathbb{E}_{\Delta}\left[\underbrace{(I_{s}(G(u_{h}^{s})) - Q_{N}(G(u_{h}^{s}), z, \Delta))^{2}}_{\text{QMC integration error}} + 2\underbrace{(\mathbb{E}[G(u)] - I_{s}(G(u^{s})))^{2} + 2\underbrace{(I_{s}(G(u^{s})) - I_{s}(G(u_{h}^{s})))^{2}}_{\text{finite element error}}\right]^{2}$$

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- Estimates for dimension truncation and finite element error known
- QMC error contribution can be bounded (using known error bounds for CBC-type constructions)

Worst-case error

For a Banach space $(\mathcal{F}, \|\cdot\|_{\mathcal{F}})$ and a QMC rule Q_N with point set $P_N = \{\boldsymbol{y}_1, \dots, \boldsymbol{y}_N\} \subset [0, 1]^s$ the *worst-case error* is defined as

$$e_{N,s}(Q_N,\mathcal{F}) := \sup_{\|\mathcal{F}\|_{\mathcal{F}} \leq 1} \left| \int_{[0,1]^s} \mathcal{F}(\boldsymbol{y}) \, \mathrm{d}\boldsymbol{y} - \frac{1}{N} \sum_{k=1}^N \mathcal{F}(\boldsymbol{y}_k) \right|.$$

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Function space setting: Weighted, unanchored Sobolev space $W_{s,\gamma}$ defined over $[-\frac{1}{2}, \frac{1}{2}]^s$ with square integrable mixed first derivatives and non-negative weights $\gamma = (\gamma_u)_{u \subseteq \{1:s\}}$. The norm for $F \in W_{s,\gamma}$ equals

$$\|F\|_{\mathcal{W}_{s,\gamma}}^2 := \sum_{\mathfrak{u} \subseteq \{1:s\}} \gamma_{\mathfrak{u}}^{-1} \int_{[-\frac{1}{2},\frac{1}{2}]^{|\mathfrak{u}|}} \left(\int_{[-\frac{1}{2},\frac{1}{2}]^{s-|\mathfrak{u}|}} \frac{\partial^{|\mathfrak{u}|}F}{\partial \boldsymbol{y}_{\mathfrak{u}}}(\boldsymbol{y}_{\mathfrak{u}};\boldsymbol{y}_{-\mathfrak{u}}) \, \mathrm{d}\boldsymbol{y}_{-\mathfrak{u}} \right)^2 \mathrm{d}\boldsymbol{y}_{\mathfrak{u}}.$$

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• We will consider lattice rules, a special family of QMC rules:

Definition: Rank-1 lattice rule

A rank-1 lattice rule is a quasi-Monte Carlo method of the form

$$Q_N(f, \mathbf{z}) := \frac{1}{N} \sum_{k=0}^{N-1} f\left(\left\{\frac{k\mathbf{z}}{N}\right\}\right),$$

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Figure 2: Fibonacci lattice with N = 55 and z = (1, 34) (left) and a rank-1 lattice with N = 32 and z = (1, 9) constructed by the CBC construction (right)

• Regularity analysis reveals that derivative bounds of POD form, i.e.,

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- \bullet Using the definition of the norm $\|\cdot\|_{\mathcal{W}_{s,\gamma}}$ this leads to the estimate

$$\|G(u_h^s)\|_{\mathcal{W}_{s,\gamma}} \leq C \, \|f\|_{V^*} \|G\|_{V^*} \left(\sum_{\mathfrak{u} \subseteq \{1:s\}} \frac{\Gamma(|\mathfrak{u}|)^2 \prod_{j \in \mathfrak{u}} b_j^2}{\gamma_{\mathfrak{u}}}\right)^{1/2}.$$

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• Using the error bound obtained for the standard CBC algorithm, the QMC error contribution can be bounded by

$$C \|f\|_{V^*} \|G\|_{V^*} C_{\gamma,\lambda} \left(\frac{2}{N}\right)^{1/2}$$

with constant

$$C_{\gamma,\lambda} := \left[\sum_{\emptyset \neq \mathfrak{u} \subseteq \{1:s\}} \gamma_{\mathfrak{u}}^{\lambda} \, \varrho^{|\mathfrak{u}|}(\lambda)\right]^{\frac{1}{\lambda}} \left[\sum_{\mathfrak{u} \subseteq \{1:s\}} \frac{\Gamma(|\mathfrak{u}|)^2 \prod_{j \in \mathfrak{u}} b_j^2}{\gamma_{\mathfrak{u}}}\right]$$

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• The resulting weights $\gamma_{\mathfrak{u}}^*$ which minimize the constant $C_{\gamma,\lambda}$ are therefore also of POD form and depend on the random field $a(\mathbf{x}, \mathbf{y})$. 8/10

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- Problem 2: Currently, the lattice rules have to be computed for every individual problem (depending on a(x, y)) leading to high computational efforts when many problems are solved.

Problem

- Device QMC finite element methods for the given PDE class that can be used simultaneously for a range of problems (without needing to construct a QMC rule repeatedly)
- Show theoretically and numerically that such methods achieve good error convergence rates

Subproblems:

- Either: Device new QMC/lattice rules which yield almost optimal error convergence rates for a large range of weight sequences
- Or: Show that existing constructions can achieve this goal provided that the weight sequences satisfy certain conditions

Thank you for your attention!